OMRON

FH-1050 FH-3050 FH-1050-

FH-3050- 0 **Image Processing System**

INSTRUCTION SHEET

Thank you for selecting OMRON product. This sheet primarily describes precautions required in installing and operating the product.

Before operating the product, read the sheet thoroughly to acquire sufficient knowledge of the product. For your convenience, keep the sheet at your disposal.

TRACEABILITY INFORMATION

Manufacturer
Omron Corporation,
Sensing Devices & Components Div.H.Q.,
Application Sensors Division
Shiokoji Horikawa, Shimogyo-ku,
Kyoto, 600-8530 JAPAN

The following notice applies only to products that carry the CE mark

voluce: This is a class A product. In residential areas it may cause radio interference, in which case the user may be required to take adequate measures to reduce interference.



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Meanings of Signal Words

Symbols and the meanings for safety precautions described in this manual.

In order for the product to be used safely, the following indications are used in this book to draw your attention to the cautions. The cautions with the indications describe the important contents for safety.



Indicates a potentially hazardous situation which, if not avoided, will result in minor or moderate injury, or may result in serious injury or death. Additionally there may be significant property damage



Indicates a potentially hazardous situation which, if not avoided, may result in minor or moderate injury or in property damage.

Meanings of Alert Symbols

The following alert symbols are used in this manual.



Indicates general prohibitions for which there is no specific symbol Indicates the possibility of electric shock under



specific conditions Indicates the possibility of explosion under



Indicates the possibility of laser radiation.

specific conditions.





Indicates the possibility of injury by high temperature under specific conditions

Alert statements in this Manual

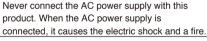
The following alert statements apply to the products in this manual. Each alert statement also appears at the locations needed in this manual to attract your attention.

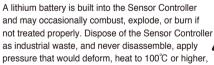
! WARNING

This product must be used according to the instruction manual. Failure to observe this may result in impairment of functions and performance of the product.



This product is not designed or rated for ensuring safety of persons. Do not use it for such purposes







Since camera that can be connected with this product emits a visible light that may have an adverse effect on the eyes, do not stare directly into the light emitted from the LED. If a specular object is used, take care not to allow reflected light enter your eyes.

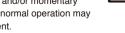
or incinerate the Sensor Controller



Please take external safety measures so that the system as a whole should be on the safe side even if a failure of a Sensor Controller or an error due to an external factor occurred. An abnormal operation may result in serious accident



Please take fail-safe measures on your side in preparation for an abnormal signal due to signal conductor disconnection and/or momentary power interruption. An abnormal operation may result in a serious accident



CAUTION

Danger of burns. Do not touch the case while the LED is ON or just after power is turned OFF, since it remains extremely hot.



Precautions for Safe Use

- Installation Environment
- · Do not use the product in areas where flammable or explosive gases are present.
- Install the product so that air can flow freely through its cooling vents · Clean the vent hole and discharge opening to prevent dust or particles from blocking them. Blocked cooling vents or discharge opening of the fan increasing heat inside, causing malfunction of
- Do not install the product close to high-voltage devices and power devices in order to secure the safety of operation and
- · Make sure to tighten all installation screws securely.

- Power Supply and WiringMake sure to use the product with the power supply voltage
- specified by this manual.

 Use the specified wire size (AWG10 to 16).

 Keep the power supply wires as short as possible (Max.2m).

 Use a DC power supply with safety measures against high-voltage
- spikes(safety extra low-voltage circuits on the secondary side).

 Do the following confirmations again before turning on the power

- supply.

 Is the voltage and polarity of the power supply correct? (24VDC)

 Is not the load of the output signal short-circuited?

 Is the load current of the output signal appropriate?

 Is not the mistake found in wiring?
- Is the voltage and polarity of the encoder power(ENC0 VDD / ENC0 GND / ENC1 VDD / ENC1 GND) supply ? (5VDC)
- Ground
 The power supply circuit of the FH Sensor Controller is insul
- from the internal circuit.

 Be sure to use a base to install the camera connected with the FH Sensor Controller. Since the exclosure of the camera main body made of metals is short-circuited with the internal circuit, the internal circuit might be short-circuited with the internal circuit, the internal circuit might be short-circuited with FG if no base is used, so that failures or malfunctions may be caused.

 Perform Class D-class grounding (with a grounding resistance of

- Keep the ground line as short as possible by setting the grounding point as close as possible.
 Ground the FH Sensor Controller independently. If sharing the ground line with other devices or connecting it with a building beam, the Sensor Controller might be adversely effected. Check wiring again before turning on the FH Sensor Controller
- Other
- Use only the camera and cables designed specifically for the product. Use of other products may result in malfunction or damage of the product.

 Always turn OFF the FH Sensor Controller's power before
- connecting or disconnecting a camera or cable. Connecting the cable with power supplied may result in damage of the camera or
- peripheral devices.

 For the cable that is flexed repeatedly, use the robotic cable type (Bend resistant camera cable) to prevent damages.

 Do not apply torsion stress to the cable. It may damage the cable.
- Secure the minimum bending radius of the cable. Otherwise the
- Secure the finitinitini relation radius of the cable. Otherwise the cable may be damaged.
 Do not attempt to dismantle, repair, or modify the product.
 Should you notice any abnormalities, immediately stop use, turn OFF the power supply, and contact your OMRON representative.
 The FH Sensor Controller and camera case are hot while power is supplied or directly after the FH Sensor Controller is turned off. Do not touch the case
- not touch the case.

 Be sure to dispose of the product as industrial waste.

 Do not drop, impose excessive vibration or shock on the product. Doing so may result in malfunction or burning.

 Since a lithium battery is incorporated, there is a rare case when you are seriously injured due to firing or blowout.
- Regulations and Standards The FH Sensor Controller is compliant with the standards
- EC Directive, 2004/108/EC EN (European Norm), EN61326-1 UL standard, UL508
- 용 Regulations of KC marking A 급 기기 (업무용 방송통신기자재) 이 기기는 업무용(A 급) 전자파적합기기로서 판매자 또는 사용자는 이 점을 주의하시기 바라며,가정외의 지역에서 사용하는 것을 목적으로 합니다.

Precautions for Correct Use

- Installation and Storage Sites
 Install and store the product in a location that meets the following conditions:
- Surrounding temperature of 0 to 50°C (-20 to +65°C in storage)

 No rapid changes in temperature (place where dew does not form)
- Relative humidity of between 35 to 85 %
- No presence of corrosive or flammable gases
 Place free of dust, salts and iron particles
- · Place free of vibration and shock
- Place out of direct sunlight
 Place where it will not come into contact with water, oils or chemicals
- Orientation of Product

To keep proper ventilation, install the main unit only in the direction below so that the ventilation holes are not blocked



Do not install in this orientation



- Ambient Temperature
- To keep proper air flow, keep the top of the FH Sensor Controller 50mm or more apart from other devices. Install the FH Sensor Controller with a clearance of 30mm on the right, left side, and
- 15mm for rear planes.

 Do not install the product immediately above significant heat
- sources, such as heaters, transformers, or large-capacity resistors.

 Do not let the ambient temperature exceed 50°C(122°F).

 Provide a forced-air fan cooling or air conditioning if the ambient temperature is near 50°C(122°F) so that the
- ambient temperature never exceeds 50°C(122°F).

 ●Noise Resistance

 Do not install the product in a cabinet containing high-voltage
- Do not install the product within 200 mm of power cables. Component Installation and Handling
- Touching Signal Lines
 To prevent damage from static electricity, use a wrist strap or another device for preventing electrostatic discharges when touching terminals or signal lines in connectors.
- Handling a USB Memory/SD memory card To remove a USB memory or SD memory card, make sure that
- data is not being read or written to it.

 For USB memory, the LED flashes while data is being read or written, so make sure that it is lit steadily before removing the
- For SD memory card, the SD BUSY LED flashes while data is being read or written, so make sure that it is turned OFF before removing the memory.
- Do not turn OFF the power while a message is being displayed indicating that processing is being performed. Data in memory wi be corrupted, and the product may not operate correctly the next time it is started.
- Turn OFF the power and take safety precautions before conducting inspections. Electrical shock can result from attempting safety
- inspections with the power turned ON.
 Clean the lens with a lens-cleaning cloth or air brush. · Lightly wipe off dirt with a soft cloth
- Dirt on the image element must be removed using an air brush.
 Do not use thinners or benzene. Communication with High-order Device
- After confirming that this product is started up, communicate with the high-order device. When this product has started up, an indefinite signal may be output from the high-order interface. To avoid this problem, clear the receiving buffer of your device at initial
- Fail-Safe Measures
- If you wish to operate a stage and/or a robot using a measurement result from a FH Sensor Controller(e.g. axis movement amount output based on calibration/alignment measurement) always take safety measures so that the measurement result should be checked by the stage/robot if it is within the range of movement of the stage/robot before operation.
- On a FH Sensor Controller side, supplementarily use operations and branches of the FH Sensor Controller to configure a check flow such as "data should not be externally provided if the data is in a range from-XXXXX to XXXXX "based on the stage/robot's

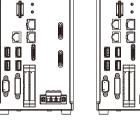
■Basic Configuration

Items indicated with an asterisk are dedicated items, and cannot be substituted

Sensor controller

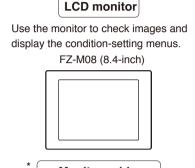
The Sensor Controller performs the image processing specified by the user settings and outputs the measurement results

Camera 2ch type Camera 4ch type Camera 8ch type FH-3050-20 FH-3050 FH-3050-10 FH-1050 FH-1050-10 FH-1050-20









Monitor cable FZ-VM (2m, 5m, min. bending radius: 75mm)

Monitor conversion connector

FH-VMRGB

Camera cable

Camera cable FZ-VS (2m, 5m, 10m, min. bending radius: 69mm)

Bend resistant camera cable FZ-VSB (2m, 5m, 10m min. bending radius: 69mm)

Right-angle camera cable FZ-VSL (2m,5m,10m min. bending radius: 69mm)

Long-distance camera cable FZ-VS2 (15m min. bending radius: 93mm) Long-distance Right-angle camera cable FZ-VSL2 (15m min. bending radius: 93mm)

Camera

Detects workpieces as images

Standalone camera

FZ-SC/FZ-S/ FZ-SC2M/FZ-S2M/

FZ-SFC/FZ-SF/

FZ-SPC/FZ-SP/

FZ-SHC/FZ-SH/ FH-SC/FH-SM/

FH-SC02/FH-SM02/

FH-SC04/FH-SM04/ FZ-SC5M2/FZ-S5M2

Intelligent compact camera FZ-SQ010F/FZ-SQ050F/

FZ-SQ100F/FZ-SQ100N Intelligent camera FZ-SLC15/FZ-SLC100

Automatic focus camera

FZ-SZC15/FZ-SZC100

Peripheral Device

- * USB memory FZ-MEM2G FZ-MEM8G
- * SD memory card HMC-SD291 HMC-SD491

Power Supply

The power supply connected to FH Sensor Controller varies depending on the number of connected cameras and types for various consumption current types. Use is accordingly. Recommended Model by OMRON:

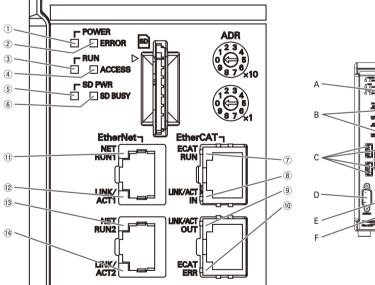
S8VS series S8VS-09024, S8VS-12024 S8VS-18024, S8VS-24024 S8VS-48024

Input Device

Mouse, keyboard (Commercially available USB devices)

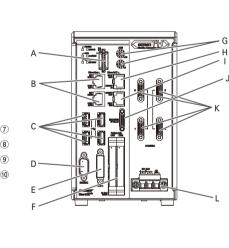
Component Names and Functions

ı		LED name	Description			
	1	POWER LED	Lit while power is ON.			
	2	ERROR LED	Lit when an error has occurred.			
	3	RUN LED	Lit while the layout turned on output setting is displayed.			
	4	ACCESS LED	Blinks while the internal nonvolatile memory is accessed.			
	(5)	SD POWER LED	Lit while power is supplied to the SD memory card and the card is usable.			
	6	SD BUSY LED	Blinks while the SD memory card is accessed.			
	7	EtherCAT RUN LED	Lit while EtherCAT communications are usable.			
	8	EtherCAT LINK/ACT IN LED	Lit when connected with an EtherCAT device, and blinks while performing communications			
	9	EtherCAT LINK/ACT OUT LED	Lit when connected with an EtherCAT device, and blinks while performing communications			
	10	EtherCAT ERR LED	Lit when EtherCAT communications have become abnormal.			
	11)	EtherNet NET RUN1 LED	Lit while EtherNet communications are usable.			
	12	EtherNet NET LINK/ACK1 LED	Lit when connected with an EtherNet device, and blinks while performing communications.			
	13	EtherNet NET RUN2 LED	Lit when EtherNet communications are usable.			
I	14)	EtherNet NET LINK/ACK2 LED	Lit when connected with an EtherNet device, and blinks while performing communications.			



Description

Connector name



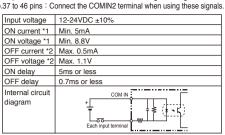
А	SD memory card installation connector	Install the SD memory card. Do not plug or unplug the SD memory card during measurement operation. Otherwise measurement time may be affected or data may be destroyed.				
В	EtherNet connector	Connect an EtherNet device.				
		Camera 2ch type Camera 4ch / 8ch type				
		Ethernet port and EtherNet/IP port are sharing use.				
С	USB connector	Connect a USB device. Do not plug or unplug it during measurement. Measurement time might be affected otherwise.				
D	RS-232C connector	Connect an external device such as a PLC.				
Е	DVI-I connector	Connect a monitor.				
F	I/O(Parallel) connector(control lines, data lines)	Connect the controller to external devices such as a sync sensor and PLC.				
G	EtherCAT address setup volume	Used to set a station address (00 to 99) as an EtherCAT communication device.				
Н	EtherCAT communication connector (IN)	Connect the opposed EtherCAT device.				
1	EtherCAT communication connector (OUT)	Connect the opposed EtherCAT device.				
J	Encoder connector	Connect an encoder.				
K	Camera connector	Camera connector No. is consistent with Camera Image Input No. of Sensor controller software. Check and connect them.				
L	Power supply terminal connector	Connect a DC power supply. Wire the FH Sensor Controller independently on other devices. Wire the ground line. Be sure to ground the FH Sensor Controller alone. Perform wiring using the attached terminal block connector as referring to the description of wiring that connector.				

■Parallel Interface

Common use to all NPN/PNP models. Wire appropriately according to the specification of the external device. ●Internal Specification (for NPN Connection)

[Input] Applicable signals/

No.14 pin: Connect the COMIN1 terminal when using these signals.
No.37 to 46 pins: Connect the COMIN2 terminal when using these signals.



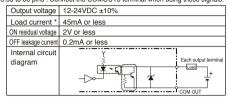
*1 ON current/voltage means the current or voltage value to activate the terminal. The ON voltage value is the potential difference between COM IN and each input terminal.

[Output] Applicable signals/ No.15 to 19 pin, No.28 to 32pin : Connect the COMOUT0 terminal when using

these signals.

No.48 to 57 pins: Connect the COMOUT2 terminal when using these signals.

No.58 to 66 pins: Connect the COMOUT3 terminal when using these signals.



The current value must be the specified load current or lower Exceeding the specified current value may cause damage of the output circuit.

Internal Specification (for PNP Connection)

[Input] Applicable signals/ No.14 pin : Connect the COMIN1 terminal when using these signals.
No.37 to 46 pint : Connect the COMIN2 terminal when using these signals.

Input voltage	12-24VDC ±10%
ON current *1	Min. 5mA
ON voltage *1	Min. 8.8V
OFF current *2	Max. 0.5mA
OFF voltage *2	Max. 1.1V
ON delay	5ms or less
OFF delay	0.7ms or less
Internal circuit diagram	Each input terminal

*1 ON current/voltage means the current or voltage value to activate the terminal. The ON voltage value is the potential difference between COM IN and each input terminal.

[Output] Applicable signals/ No.15 to 19 pin, No.28 to 32 pin : Connect the COMOUT0 terminal

when using these signals.

No.48 to 57 pins : Connect the COMOUT2 terminal when using these signals.

No.58 to 66 pins : Connect the COMOUT3 terminal when using these signals.

	on the control of the					
Output voltage	12-24VDC ±10%					
Load current *	45mA or less					
ON residual voltage	2V or less					
OFF leakage current	0.2mA or less					
Internal circuit diagram	COM OUT + Com Each output terminal					

* The current value must be the specified load current or lower Exceeding the specified current value may cause damage of the output circuit.

[Input] Applicable signals/

No.4 to 6, 9 to 11 pins: Connect the COMIN1 terminal when using these signals. No.7, 8, 12, 13 pins: Connect the COMIN0 terminal when using these signals.

VU.	10.7, 0, 12, 13 pins . Confident the Colvinio terminal when using these signals.					
	Input voltage	12-24VDC ±10%				
	ON current *1	Min. 5mA				
	ON voltage *1	Min. 8.8V				
	OFF current *2	Max. 0.5mA				
	OFF voltage *2	Max. 0.8V				
	ON delay	0.1ms or less				
	OFF delay	0.1ms or less				
	Internal circuit	COM IN				
	diagram	+				
		Each input terminal				
		L				

*2 OFF current/voltage means the current or voltage value to deactivate the terminal. The OFF voltage value is the potential difference between COM IN and each input terminal.

[Output] Applicable signals/

No.20 to 27 pins : Connect the COMOUT1 and COMIN0 terminals when

Output voltage	12-24VDC ±10%
Load current *	45mA or less
ON residual voltage	2V or less
OFF leakage current	0.2mA or less
Internal circuit diagram	COM NV Extra cuptor of the cu

[Input] Applicable signals/ No.4 to 6, 9 to 11 pins: Connect the COMIN1 terminal when using these signals. No.7, 8, 12, 13 pins: Connect the COMIN0 terminal when using these signals.

Input voltage	12-24VDC ±10%			
ON current *1	Min. 5mA			
ON voltage *1	Min. 8.8V			
OFF current *2	Max. 0.5mA			
OFF voltage *2	Max. 0.8V			
ON delay	0.1ms or less			
OFF delay	0.1ms or less			
Internal circuit diagram	Each input terminal			

*2 OFF current/voltage means the current or voltage value to activate the terminal. The OFF voltage value is the potential difference between COM IN

[Output] Applicable signals/ No.20 to 27 pins : Connect the COMOUT1 and COMIN0 terminals when using these signals.

Output volta	age	12-24VDC ±10%
Load curre	nt *	45mA or less
ON residual vo	ltage	2V or less
OFF leakage cu	ırrent	0.2mA or less
Internal cir diagram	cuit	COM OUT Each output We mind COM N
1		Com in

The role of terminals varies depending on the settings of FH Sensor Controller. Check the settings and perform correct wiring.

			Signa	ıl name						
No	I/O	In the 1-line mode	In the 2-line random mode		In the 5 to 8-line random mode	Remarks				
1	-		COI							
2	-		COI							
3	-	OTERN ELICTRIC TO (III)		acant	OTERA					
5	IN IN	STEP0/ENCTRIG_ZO (*1) Unused (*5)	STEP0/ENCTRIG_ZO (*2) STEP1/ENCTRIG_Z1 (*2)	STEP0 STEP1	STEP0 STEP1					
6	IN	Unused (*5)	Unused (*5)	STEP2	STEP2					
7	IN	Unused (*5)	Unused (*5)	STEP3	STEP3					
8	IN	ENCTRIG_AO (*1)	ENCTRIG_A0 (*2)	Unused (*5)	Unused (*5)					
9	IN	Unused (*5)	Unused (*5)	Unused (*5)	STEP4					
10	IN	Unused (*5)	Unused (*5)	Unused (*5)	STEP5					
11	IN	Unused (*5)	ENCTRIG_A1 (*2)	Unused (*5)	STEP6					
12	IN IN	Unused (*5) ENCTRIG_B0 (*1)	ENCTRIG_B1 (*2) ENCTRIG_B0 (*2)	Unused (*5) Unused (*5)	STEP7 Unused (*5)					
14	IN	Unused (*5)	DILI		Oliuseu (5)					
15	OUT	RUN0	RUN0	RUN0	READY0					
16	OUT	READY0	READY0	READY0	BUSY0					
17	OUT	BUSY0	BUSY0	BUSY0	OR0					
18	OUT	OR0	OR0	OR0	READY1					
19	OUT	ERRORO	ERROR0	ERRORO	BUSY1					
20	OUT	STGOUT0 (*3)/SHTOUT0 STGOUT1 (*3)	STGOUT0 (*3)/SHTOUT0 STGOUT1 (*3)/SHTOUT1	STGOUTO (*3)/SHTOUTO STGOUT1 (*3)/SHTOUT1	STGOUT0 (*3)/SHTOUT0 STGOUT1 (*3)/SHTOUT1					
22	OUT	STGOUT2 (*3)	STGOUT2 (*3)	STGOUT2 (*3)/SHTOUT2	STGOUT2 (*3)/SHTOUT2					
23	OUT	STGOUT3 (*3)	STGOUT3 (*3)	STGOUT3 (*3)/SHTOUT3	STGOUT3 (*3)/SHTOUT3	COMIN0 to 2 : Common 0 to 2 for input signals				
24	OUT	STGOUT4 (*3)	STGOUT4 (*3)	STGOUT4 (*3)	STGOUT4 (*3)/SHTOUT4	COMOUT0 to 3 : Common 0 to 3 for output signals				
25	OUT	STGOUT5 (*3)	STGOUT5 (*3)	STGOUT5 (*3)	STGOUT5 (*3)/SHTOUT5					
26	OUT	STGOUT6 (*3)	STGOUT6 (*3)	STGOUT6 (*3)	STGOUT6 (*3)/SHTOUT6	DI0 to 7 : Command inputs				
27	OUT	STGOUT7 (*3)	STGOUT7 (*3)	STGOUT7 (*3)	STGOUT7 (*3)/SHTOUT7	DILINE0 to 2 : Command inputs (line specified)				
29	OUT	Unused (*5) Unused (*5)	RUN1 READY1	RUN1 READY1	OR1 READY2	DSA0 to 1 : Data transmission request ENCTRIG_A0 to 1 : Encoder trigger input (phase A)				
30	OUT	Unused (*5)	BUSY1	BUSY1	BUSY2	ENCTRIG_B0 to 1 : Encoder trigger input (phase A)				
31	OUT	Unused (*5)	OR1	OR1	OR2	ENCTRIG_Z0 to 1 : Encoder trigger input (phase Z)				
32	OUT	Unused (*5)	ERROR1	ERROR1	READY3	STEP0 to 7 : Measurement trigger input				
33	_			OUT0						
34	-		COM	OUT1		ACK: Instruction execution completion flag				
35	_			MIN2		BUSY0 to 7: ON during processing DO0 to 15: Data output				
36	_			ıcant		ERROR: ON when an error occurs (*4)				
37	IN	DSA0	DSA0	DILINE1	DILINE1	ERROR0 to 3 : ON when an error occurs				
38	IN	Unused (*5)	DSA1	Unused (*5)	DILINE2	GATE0 to 1 : ON during configured output time				
39	IN		D			OR0 to 7: Overall judgement result				
40	IN		D			READY0 to 7: ON when image input is allowed				
41	IN		D			RUN0 to 3 : ON while the layout turned on output setting is displayed				
42	IN IN		D D			SHTOUT0 to 7 : Shutter output				
44	IN		D			STGOUT0 to 7 : Strobe trigger output(*3)				
45	IN		D							
46	IN		D	17						
47	_			ant						
48	OUT	CATEO	AC		DUOVO					
49 50	OUT	GATE0 Unused (*5)	GATE0 GATE1	RUN2 READY2	BUSY3 OR3					
51	OUT	DO0	DO0	BUSY2	READY4					
52	OUT	DO1	DO1	OR2	BUSY4					
53	OUT	DO2	DO2	ERROR2	OR4					
54	OUT	DO3	DO3	RUN3	READY5					
55	OUT	DO4	DO4	READY3	BUSY5					
56	OUT	DO5	DO5	BUSY3	OR5					
57 58	OUT	DO6 DO7	DO6 DO7	OR3 ERROR3	READY6					
58	OUT	DO8	DO7	Unused (*5)	BUSY6 OR6					
60	OUT	DO9	DO9	Unused (*5)	READY7					
61	OUT	DO10	DO10	Unused (*5)	BUSY7					
62	OUT	DO11	DO11	Unused (*5)	OR7					
63	OUT	DO12	DO12	Unused (*5)	Unused (*5)					
64	OUT	DO13	DO13	Unused (*5)	Unused (*5)					
65	OUT	DO14	DO14	Unused (*5) Unused (*5)	Unused (*5)					
66 67	OUT —	DO15	DO15 COM	ERROR (*4)						
68	_			OUT3						
_		se a measurement trigger input, use the STEP signal. To use an encoder input, use ENCTRIG, A0/B0/70								

*1 To use a measurement trigger input, use the STEP signal. To use an encoder input, use ENCTRIG A0/B0/Z0.

*2 In the 2-line random mode, to use a measurement trigger input and a line of encoder input, use ENCTRIG_A0/B0/Z0 and STEP1.

*3 This is the signal used when using a strobe signal for the FH Sensor Controller.

*4 This is the ERROR signal commonly used in 1 to 8-line modes.

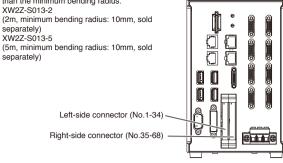
*5 Do not connect anything for Unused.

Connection

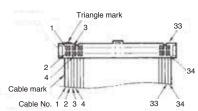
Connect the parallel I/O cable with more than the minimum bending radius. XW2Z-S013-2

(2m, minimum bending radius: 10mm, sold separately)

separately)



Pin Assignment



Use another XW2Z-S013-☐ for No.35 to 68.

■Encoder Interface (Line Driver Type)

Specification of Encoder Interface (Line Driver Output Type)

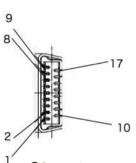
Item	Specifications
Input voltage	Input voltage : 5VDC±5% Signal level : EIA Standard, RS-422-A line driver level
Input impedance *1	120Ω±5%
Differential input voltage	High-level input voltage I 0.1V, Low-level input voltage I -0.1V
Hysteresis voltage	60mV
Maximum response frequency *2	Phase A/B: single-phase 4MHz (multiplying phase difference of 1MHz by 4 times), Phase Z: 1MHz (When using an I/O cable, model FH-VR 1.5M)

*1 Value when the terminal resistance function is used.

*2 Use this interface as paying attention to the cable length and response frequency of the encoder used

■I/O Connector

UI/O Connector						
No	Signal name	Color	Remarks			
1	ENC0 A+	Black	Signal : Ch1 A-Phase(+)			
2	ENC0 A-	Black /Red	Signal : Ch1 A-Phase(-)			
3	ENC0 VDD	Brown	Power : Power supply for Ch1 (5VDC)			
4	ENC0 B+	White	Signal : Ch1 B-Phase(+)			
5	ENC0 B-	White/Red	Signal : Ch1 B-Phase(-)			
6	ENC0 GND	Blue	Power : Signal ground for Ch1 (0V)			
7	ENC0 Z+	Orange	Signal : Ch1 Z-Phase(+)			
8	ENC0 Z-	Orange/Red	Signal : Ch1 Z-Phase(-)			
9	NC	_	Not connected			
10	ENC1 A+	Purple	Signal : Ch2 A-Phase(+)			
11	ENC1 A-	Purple/Red	Signal : Ch2 A-Phase(-)			
12	ENC1 VDD	Brown/Red	Power : Power supply for Ch2 (5VDC)			
13	ENC1 B+	Pink	Signal : Ch2 B-Phase(+)			
14	ENC1 B-	Pink/Red	Signal : Ch2 B-Phase(-)			
15	ENC1 GND	Blue/Red	Power : Signal ground for Ch2 (0V)			
16	ENC1 Z+	Yellow	Signal : Ch2 Z-Phase(+)			
17	ENC1 Z-	Yellow/Red	Signal : Ch2 Z-Phase(-)			

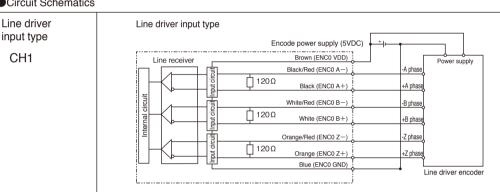


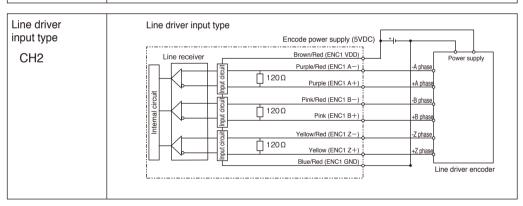
Connection

Connect the encoder cable with more than the minimum bending radius. FH-VR 1.5M (1.5m, minimum bending radius: 65mm, sold separately)



Circuit Schematics





■Camera cable

The maximum cable length depends on the Camera being connected, and the model and length of the Cable being used. For further information, please refer to the "Cameras/Cables Connection Table". Be sure to secure at least the minimum bending radius of the cable

Cameras/Cables Connection Table(Connecting to FH-S Series Camera)

	Model	Cable length	High-speed CMOS cameras *				
			300,000-pixel	2 million-pixel		4 million-pixel	
Type of			FH-SM/SC	FH-SM02/SC02		FH-SM04/SC04	
camera			_	High speed mode of transmission speed select	Standard mode of transmission speed select	High speed mode of transmission speed select	Standard mode of transmission speed select
Camera Cable	FZ-VS FZ-VSL	2m	Yes	Yes	Yes	Yes	Yes
Right-angle		5 m	Yes	Yes	Yes	Yes	Yes
camera cable		10 m	Yes	No	Yes	No	Yes
Bend resistant	FZ-VSB	2m	Yes	Yes	Yes	Yes	Yes
camera cable		5 m	Yes	Yes	Yes	Yes	Yes
		10 m	Yes	No	Yes	No	Yes
Long-distance camera cable Long-distance right-angle camera cable	FZ-VS2 FZ-VSL2	15 m	Yes	No	Yes	No	Yes

*High-speed CMOS camera is only for the FH series.

Cameras/Cables Connection Table(Connecting to FZ-S Series Camera)

Total ordered activities and transfer in the second activities and the second activities are second activities and the second activities and the second activities and the second activities are second activities and the second activities and the second activities activities and the second activities are second activities and the second activities activities and the second activities activities and the second activities a										
			Digital CCD cameras			Small digital	High-speed	Intelligent	Intelligent CCD	
Type of camera	Model	Cable length	300,000-pixel	2 million-pixel	5 million-pixel	CCD cameras Pen type/flat type	CCD camera	compact CMOS cameras	cameras Autofocus CCD cameras	
		longth	FZ-S/SC	FZ-S2M/SC2M	FZ-S5M2/ SC5M2	FZ-SF/SFC FZ-SP/SPC	FZ-SH/SHC	FZ-SQ□	FZ-SLC□ FZ-SZC□	
Camera Cable	FZ-VS	2m	Yes	Yes	Yes	Yes	Yes	Yes	Yes	
Right-angle camera cable	FZ-VSL	5 m	Yes	Yes	Yes	Yes	Yes	Yes	Yes	
		10 m	Yes	Yes	No	Yes	Yes	Yes	No	
Bend resistant	FZ-VSB	2m	Yes	Yes	Yes	Yes	Yes	Yes	Yes	
camera cable		5 m	Yes	Yes	Yes	Yes	Yes	Yes	Yes	
ourrora oabio		10 m	Yes	Yes	No	Yes	Yes	Yes	No	
Long-distance camera cable Long-distance right-angle camera cable	FZ-VS2 FZ-VSL2	15 m	Yes	Yes	No	Yes	Yes	Yes	No	

Mounting of Ferrite core

Mount the ferrite core attached to the camera cable to near the Sensor Controller.





■EtherCAT Interface

Cable Connect a straight LAN cable.

Use an STP cable of category 5e or higher, which is shielded double with an aluminum tape and a braided cord.

●I/O Connector Use an 8-pin shielded RJ45 modular connecter of category 5e or higher.



π	Pin No.	Signal name	Abbreviation	Signal direction
	1	Transmission data +	TD+	Out
	2	Transmission data -	TD-	Out
	3	Reception data +	RD+	In
	4	Not connected	NC	_
	5	Not connected	NC	_
	6	Reception data -	RD-	In
	7	Not connected	NC	_
	8	Not connected	NC	_
	Connector hood	Security ground	FG	_

Wiring

The cable is maximum 100m long.

However, some cables do not guarantee 100m. If conductor is a twisted cable, transmission performance generally becomes worse than that of straight cables, so that 100m cannot be guaranteed. For details, contact the cable manufacturer

Pin No.	Wire color]	Wire color	Pin No.
1	White · Green	$\vdash \land \land \vdash$	White ⋅ Green	1
2	Green		Green	2
3	White · Orange		White · Orange	3
4	Blue	 	Blue	4
5	White · Blue		White · Blue	5
6	Orange		Orange	6
7	White · Brown	 	White · Brown	7
8	Brown] 	Brown	8
Connector hood	Shielded cable		Shielded cable	Connector hood

Connect both ends of the cable shield with the connector hood Use the T568A wiring method as mentioned above.

■RS-232C(Serial) Interface

Not connected Data reception

Not connected

Signal ground

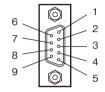
Not connected

Not connected

Not connected

●I/O Connector

Wiring



Pin No. Signal name Function

SD

GND

FH Sensor Controller Signal name Pin No.				
Signal name Pin No.				
RD	2	_		

The maximum cable length is 15m.

FH Sensor	Controller	
Signal name	Pin No.	/
RD	2	\rightarrow
SD	3	-+
GND	5	-+

Sensor	Controller				External device	to be connecte
name	Pin No.]	\bigcap		Pin No.	Signal name
)	2			\rightarrow	*	RD
)	3			-	*	SD
D	5		\backslash		*	GND
			V		RS/CS control	cannot be us

Use a shielded cable

Use a compatible connector.

Recommended items

	Manufacturer	Model
Sockets	OMRON Corporation	XM3D-0921
Hood	OMRON Corporation	XM2S-0913

Pin numbers will depend on the external device being connected. Refer to the manual for the personal computer or PLC being connected.

Terminal block connector (male)

NC Connection Method

Align the connector with the socket and press it straight into place, then fix it with the screws on both sides of the connector.

Turn OFF the power supply before connecting or disconnecting a Parallel I/O Cable Peripheral devices may be damaged if the cable is connected or disconnected with the power ON.

Wiring

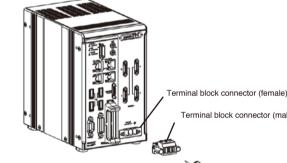
[Important] - Wiring cables incorrectly might cause failures. Connection of Terminal Block

Insert the end of the signal line (electric wire) into the terminal block connector (male), and tighten the three screws on the connector top to fix the wire.

Recommended tightening torque: 0.7-0.8N·m Insert the terminal block connector (male) into the terminal block connector (female) on the FH Sensor Controller side.

Fix the terminal block connector (male) by tightening the screws on the right and left sides of it with a flathead screwdriver. Recommended tightening torque: 0.7-0.8N·m ITACT)

Terminal blo	ck connec	ctor(male):PC	25/3-STF1-7.62 BK(PHOENIX CONT
Pin No.	Display	Signal name	Function
1	+	24V	Input power supply voltage (24VDC).
2	_	OV	Input power supply voltage (0V).
_		ONID	Invest OND



GND Input GND. The power supply connected to the FH Sensor Controller varies depending on the number of connected cameras and types. Use it accordingly

Recommended power supply

Item	Comoro tino	No. of cameras	Н	ligh-speed controll	er	Standard controller		
	Camera type	connected	FH-3050	FH-3050-10	FH-3050-20	FH-1050	FH-1050-10	FH-1050-20
Recommended power supply: S8VS		2	S8VS-12024	S8VS-18024	S8VS-18024	S8VS-12024	S8VS-12024	S8VS-18024
	Intelligent camera	4	-	S8VS-18024	S8VS-24024		S8VS-18024	S8VS-24024
		8		-	S8VS-48024			S8VS-48024
	Camera of 0.3/2/4/5 million	2	S8VS-12024	S8VS-18024	S8VS-18024	S8VS-09024	S8VS-09024	S8VS-12024
		4		S8VS-18024	S8VS-18024		S8VS-12024	S8VS-12024
	pixels	8	-	-	S8VS-18024	-	-	S8VS-18024

■Ratings/Characteristics

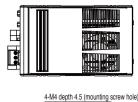
Туре				Hig	h-speed controlle	er	Sta	andard controller			
Model		NPN PNP		FH-3050	FH-3050-10	FH-3050-20	FH-1050	FH-1050-10	FH-1050-20		
	Controller type			BOX type							
	High-grade (HG) pr	rocessing item		2							
Major functions	Number of camer	Number of cameras			4	8	2	4	8		
	Type of connecte	d camera			n be connected (FZ-S/FH-S series	5)				
unctions	Number of scenes	S		128							
	Operation			Mouse or simila	ar device						
	Settings			Create processi	ng flows by editin	g them (with a gui	dance).				
	Serial commun	nications		RS-232C 1 C	Н						
	Ethernet comm	nunications		Non-procedural	(TCP/UDP) 100	OBASE-T					
	Ethernet com	nunications		1port	2port	2port	1 port	2port	2port		
	EtherNet/IP co	mmunication	าร	1 port (Ethernet	port and EtherNet/	IP port are sharing	use.) Transmissi	ion speed : 100Mbp	s (100BASE-TX		
	EtherCAT com	munications		EtherCAT dedic	ated protocol (10	0BASE-TX)					
External nterface	Parallel I/O			In the 2-line ran In the 3 to 4-line	e random trigger r	puts. e: 17 inputs, 37 o mode: 14 inputs, 3 mode: 19inputs, 3	29 outputs.				
	Encoder I/F			RS422-A line drive	r level. Phase A/B: sir	ngle-phase 4MHz (mu	Itiplying phase differ	rence of 1MHz by 4 tin	nes), Phase Z: 1MH		
	Monitor I/F			DVI-I output 1ch	1						
	USBI/F										
		SD memory card I/F			4 ch(supports USB1.1 and 2.0)						
	Power supply voltage			SDHC standard, Class 4 or higher recommended							
	Fower supply	When an intelligent compact camera or autofocus camera is connected*		20.4 to 26.4VD0		0.44		I 5 0 4 1	I = 0.4 !		
	Current consumption *		2 connected	5.0A or less	5.4A or less	6.4A or less	4.7A or less	5.0A or less	5.9A or less		
			4 connected	_	7.0A or less	8.1A or less		6.5A or less	7.5A or less		
Datings			8 connected	-	-	11.5A or less	-	-	10.9A or less		
Ratings			2 connected	4.1A or less	4.2A or less	5.2A or less	3.6A or less	3.7A or less	4.5A or less 5.0A or less		
			4 connected	_	4.8A or less	5.6A or less	_	4.3A or less			
	Inculation rec	iotonoo	8 connected		_	6.8A or less			6.2A or less		
	Insulation res	lstance		Between DC power supply and FH Sensor Controller FG: 20MΩ or higher (rated voltage 250V) Direct infusion: 2KV Pulse rising: 5ns Pulse width: 50ns							
	Noise	Fast	DC power		Burst continuation time: 15ms/0.75ms Period: 300ms Application time: 1 min						
	resistance	transient burst	I/O line		Cramp : 1KV Pulse rising: 5ns Pulse width: 50ns Burst continuation time: 15ms/0.75ms Period: 300ms Application time: 1 min						
	Ambient temper	ature range		Operating:0 to 50 °C Storage:-20 to +65 °C (with no icing nor no condensation)							
Operating	Ambienthumidi	ty range		Operating and storage: 35 % to 85 % (no condensation)							
environment	Ambientenviro	nment		No corrosive gases							
BITVITOTITIETIC	Grounding			Type D grounding (100Ω or less grounding resistance) *Conventional type 3 grounding							
	Degree of prote	ction		IEC60529 IP20							
	Environmental conditions			Indoor use Maximum altitude of 2,000m Supply voltage fluctuations of +10%, -15% of the rated voltage Installation category I Pollution degree 2							
	Dimensions			190mm(H)×115mm(W)×182.5mm(D)							
Dimensions	Weight				Approx.3.4kg	Approx.3.4kg	Approx.3.2kg	Approx.3.4kg	Approx.3.4kg		
	Case materials							1	p 3x.0. mg		
Content				Cover. zinc-plated steel plate, Side plate: aluminum (A6063) FH Sensor Controller (1) / Instruction Sheet (one Japanese and one English version) / Instruction Installation Manual (1) / Terminal block connector (1) / Ferrite core 2(FH3050 and FH-1050), 4 (FH-3050-10 and FH-1050-10), and 8 (FH-3050-20 and FH-1050-20)							

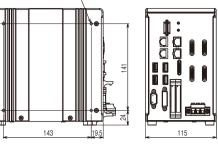
The value of power consumption applies when the maximum number of cameras of each FH Sensor Controller is connected with 24VDC. When connecting the lighting with strobe controller, the consumption current is the same as when the intelligent camera is connected

Dimensions

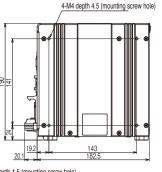
4-M4 depth 4.5 (mounting screw hole)

(Unit: mm)

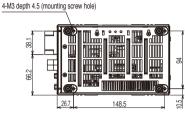


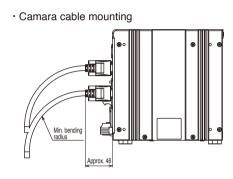








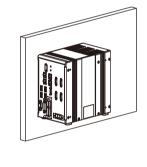


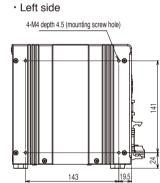


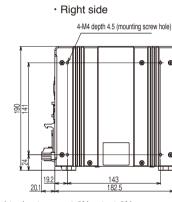
Mounting

Tighten the screws securely when installing the product.

Side Mounting





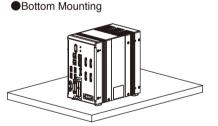


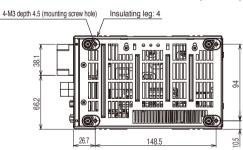
- * Recommended tightening torque: 1.2N·m to 1.3N·m
- *The tolerance is \pm 0.2mm.

Bottom

(Unit: mm)

(Unit: mm)





- * Do not remove the Insulating leg. Fix the Insulating leg to secure the ventilation path.
- * Recommended tightening torque: 0.54N·m to 0.6N·m *The tolerance is ± 0.2mm.

Suitability for Use

Omron Companies shall not be responsible for conformity with any standards, codes or regulations which apply to the combination of the Product in the Buyer's application or use of the Product. At Buyer's request, Omron will provide applicable third party certification documents identifying ratings and limitations of use which apply to the Product. This information by itself is not sufficient for a complete determination of the suitability of the Product in combination with the end product, machine, system, or other application or use. Buyer shall be solely responsible for determining appropriateness of the use: buyer shall be solely responsible to determining appropriatelless of particular Product with respect to Buyer's application, product or system Buyer shall take application responsibility in all cases.

NEVER USE THE PRODUCT FOR AN APPLICATION INVOLVING SERIOUS RISK TO LIFE OR PROPERTY WITHOUT ENSURING THAT THE SYSTEM AS A WHOLE HAS BEEN DESIGNED TO ADDRESS THE RISKS, AND THAT THE OMRON PRODUCT(S) IS PROPERLY RATED AND INSTALLED FOR THE INTENDED USE WITHIN THE OVERALL EQUIPMENT OR SYSTEM.

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DP June, 2013

following notice applies: Perchlorate Material - special handling may apply. See www.dtsc.ca.gov/hazardouswaste/perchlorate

This product contains a lithium battery for which the

■U.S. California Notice: